## **SIEMENS**

## Data sheet

6ES7511-1AK02-0AB0

SIMATIC S7-1500, CPU 1511-1 PN, CENTRAL PROCESSING UNIT WITH WORKING MEMORY 150 KB FOR PROGRAM AND 1 MB FOR DATA, 1. INTERFACE: PROFINET IRT WITH 2 PORT SWITCH, 60 NS BIT-PERFORMANCE, SIMATIC MEMORY CARD NECESSARY



General information	
Product type designation	CPU 1511-1 PN
HW functional status	FS01
Firmware version	V2.5
Engineering with	
<ul> <li>STEP 7 TIA Portal configurable/integrated as of version</li> </ul>	V15
Configuration control	
via dataset	Yes
Display	
Screen diagonal [cm]	3.45 cm
Control elements	
Number of keys	8
Mode buttons	2
Supply voltage	
Type of supply voltage	24 V DC
permissible range, lower limit (DC)	19.2 V

permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
Mains/voltage failure stored energy time	5 ms
• Repeat rate, min.	1/s
. opostosto,	
Input current	
Current consumption (rated value)	0.7 A
Current consumption, max.	0.95 A
Inrush current, max.	1.9 A; Rated value
l <sup>2</sup> t	0.02 A²·s
Power	
Infeed power to the backplane bus	10 W
Power consumption from the backplane bus	5.5 W
(balanced)	
Power loss	
Power loss, typ.	5.7 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
<ul><li>integrated (for program)</li></ul>	150 kbyte
• integrated (for data)	1 Mbyte
Load memory	
<ul> <li>Plug-in (SIMATIC Memory Card), max.</li> </ul>	32 Gbyte
Backup	
• maintenance-free	Yes
CPU processing times	
for bit operations, typ.	60 ns
for word operations, typ.	72 ns
for fixed point arithmetic, typ.	96 ns
for floating point arithmetic, typ.	384 ns
CPU-blocks	2 000: Pleate (OP, EP, EO, DP) and UPTa
Number of elements (total)  DB	2 000; Blocks (OB, FB, FC, DB) and UDTs
	4 CO 0000 subdivided into reventor regard that are he wood by
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	1 Mbyte; For non-optimized block accesses, the max. size of the DB is 64 KB
FB	
Number range	0 65 535

• Size, max.	150 kbyte
FC	
Number range	0 65 535
• Size, max.	150 kbyte
ОВ	
• Size, max.	150 kbyte
<ul> <li>Number of free cycle OBs</li> </ul>	100
<ul> <li>Number of time alarm OBs</li> </ul>	20
<ul> <li>Number of delay alarm OBs</li> </ul>	20
<ul> <li>Number of cyclic interrupt OBs</li> </ul>	20; With minimum OB 3x cycle of 500 μs
<ul> <li>Number of process alarm OBs</li> </ul>	50
<ul> <li>Number of DPV1 alarm OBs</li> </ul>	3
<ul> <li>Number of isochronous mode OBs</li> </ul>	1
<ul> <li>Number of technology synchronous alarm OBs</li> </ul>	2
<ul> <li>Number of startup OBs</li> </ul>	100
<ul> <li>Number of asynchronous error OBs</li> </ul>	4
<ul> <li>Number of synchronous error OBs</li> </ul>	2
<ul> <li>Number of diagnostic alarm OBs</li> </ul>	1
Nesting depth	
• per priority class	24
Counters, timers and their retentivity	
S7 counter	
Number	2 048
Retentivity	
— adjustable	Yes
	165
IEC counter	165
IEC counter  ● Number	Any (only limited by the main memory)
Number	
Number     Retentivity	Any (only limited by the main memory)
<ul><li>Number</li><li>Retentivity</li><li>— adjustable</li></ul>	Any (only limited by the main memory)
<ul><li>Number</li><li>Retentivity</li><li>— adjustable</li><li>S7 times</li></ul>	Any (only limited by the main memory) Yes
<ul> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>S7 times</li> <li>Number</li> </ul>	Any (only limited by the main memory) Yes
<ul> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>S7 times</li> <li>Number</li> <li>Retentivity</li> </ul>	Any (only limited by the main memory)  Yes  2 048  Yes
<ul> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>S7 times</li> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> </ul>	Any (only limited by the main memory)  Yes 2 048
<ul> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>S7 times</li> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>IEC timer</li> </ul>	Any (only limited by the main memory)  Yes  2 048  Yes  Any (only limited by the main memory)
<ul> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>S7 times</li> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>IEC timer</li> <li>Number</li> </ul>	Any (only limited by the main memory)  Yes  2 048  Yes
<ul> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>S7 times</li> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>IEC timer</li> <li>Number</li> <li>Retentivity</li> </ul>	Any (only limited by the main memory)  Yes  2 048  Yes  Any (only limited by the main memory)
<ul> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>S7 times</li> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>IEC timer</li> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> </ul>	Any (only limited by the main memory)  Yes  2 048  Yes  Any (only limited by the main memory)

Extended retentive data area (incl. timers, counters,	1 Mbyte; When using PS 60W 24/48/60V DC HF
flags), max.	
Flag	16 khyto
Number, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	V
Retentivity adjustable	Yes
Retentivity preset	No
Local data	
<ul><li>per priority class, max.</li></ul>	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	1 024; max. number of modules / submodules
I/O address area	
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
Number of subprocess images, max.	32
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	4; A maximum of 4 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
• integrated	1
• Via CM	4; A maximum of 4 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Rack	
Modules per rack, max.	32; CPU + 31 modules
<ul> <li>Number of lines, max.</li> </ul>	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots

Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
• supported	Yes
• in AS, master	Yes
• in AS, slave	Yes
• on Ethernet via NTP	Yes
nterfaces	
Number of PROFINET interfaces	1
. Interface	
Interface types	
Number of ports	2
integrated switch	Yes
• RJ 45 (Ethernet)	Yes; X1
Protocols	
• IP protocol	Yes; IPv4
<ul> <li>PROFINET IO Controller</li> </ul>	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes
Web server	Yes
Media redundancy	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	Yes
— Open IE communication	Yes
— IRT	Yes
— MRP	Yes; As MRP redundancy manager and/or MRP client; max. number of devices in the ring: 50
— MRPD	Yes; Requirement: IRT
— PROFlenergy	Yes
— Prioritized startup	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	128; In total, up to 256 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
— Of which IO devices with IRT, max.	64

<ul> <li>Number of connectable IO Devices for RT, max.</li> </ul>	128
— of which in line, max.	128
<ul> <li>Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8; in total across all interfaces
<ul> <li>Number of IO Devices per tool, max.</li> </ul>	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 250 μs	$250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625 $\mu s$ of the isochronous OB is decisive
— for send cycle of 500 μs	500 $\mu s$ to 8 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 625 $\mu s$ of the isochronous OB is decisive
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
<ul> <li>With IRT and parameterization of "odd"</li> </ul>	Update time = set "odd" send clock (any multiple of 125 µs: 375
send cycles	μs, 625 μs 3 875 μs)
Update time for RT	
— for send cycle of 250 μs	250 μs to 128 ms
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	V.
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	No
— Open IE communication	Yes
— IRT	Yes
— MRP	Yes
— MRPD	Yes; Requirement: IRT
— PROFlenergy	Yes
— Shared device	Yes
<ul> <li>Number of IO Controllers with shared device, max.</li> </ul>	4
<ul> <li>Asset management record</li> </ul>	Yes; Per user program
Interface types RJ 45 (Ethernet)	

• 100 Mbps	Yes
Autonegotiation	Yes
Autocrossing	Yes
• Industrial Ethernet status LED	Yes

<ul> <li>Industrial Ethernet status LED</li> </ul>	Yes
Protocols	
Number of connections	
Number of connections, max.	96; via integrated interfaces of the CPU and connected CPs / CMs
<ul> <li>Number of connections reserved for ES/HMI/web</li> </ul>	10
<ul> <li>Number of connections via integrated interfaces</li> </ul>	64
<ul> <li>Number of S7 routing paths</li> </ul>	16
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	Yes
— Open IE communication	Yes
— IRT	Yes
— PROFlenergy	Yes
<ul> <li>Prioritized startup</li> </ul>	Yes; Max. 32 PROFINET devices
<ul> <li>Number of connectable IO Devices, max.</li> </ul>	128; In total, up to 256 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
<ul> <li>Of which IO devices with IRT, max.</li> </ul>	64
<ul> <li>Number of connectable IO Devices for RT,</li> </ul>	128
max.	
— of which in line, max.	128
<ul> <li>Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8; in total across all interfaces
<ul> <li>Number of IO Devices per tool, max.</li> </ul>	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Redundancy mode	
— MRP	Yes; As MRP redundancy manager and/or MRP client; max. number of devices in the ring: 50
— MRPD	Yes; Requirement: IRT
SIMATIC communication	
S7 communication, as server	Yes
<ul> <li>S7 communication, as client</li> </ul>	Yes
<ul> <li>User data per job, max.</li> </ul>	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes

— Data length, max.	64 kbyte
<ul> <li>several passive connections per port,</li> </ul>	Yes
supported	
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; Max. 5 multicast circuits
• DHCP	No
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
<ul> <li>Runtime license required</li> </ul>	Yes
OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address space
<ul> <li>Application authentication</li> </ul>	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
<ul> <li>User authentication</li> </ul>	"anonymous" or by user name & password
— Number of sessions, max.	32
<ul> <li>Number of accessible variables, max.</li> </ul>	50 000
<ul> <li>Number of registerable nodes, max.</li> </ul>	10 000
<ul> <li>Subscriptions per session, max.</li> </ul>	20
— Sampling time, min.	100 ms
— Send time, min.	500 ms
<ul> <li>Number of server methods, max.</li> </ul>	20
<ul> <li>Number of inputs/outputs per server method, max.</li> </ul>	20
<ul> <li>Number of monitored items, max.</li> </ul>	1 000; For 1 s sampling interval and 1 s send interval
<ul> <li>Number of server interfaces, max.</li> </ul>	10
<ul> <li>Number of nodes for user-defined server interfaces, max.</li> </ul>	1 000
Further protocols	
• MODBUS	Yes; MODBUS TCP
Media redundancy	
Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
<ul><li>Number of stations in the ring, max.</li></ul>	50
Isochronous mode	

Isochronous operation (application synchronized up to terminal)	Yes; With minimum OB 6x cycle of 625 μs
Equidistance	Yes
S7 message functions	
Number of login stations for message functions, max.	32
Program alarms	Yes
Number of configurable program alarms	5 000
Number of simultaneously active program alarms	
<ul> <li>Number of program alarms</li> </ul>	300
<ul> <li>Number of alarms for system diagnostics</li> </ul>	100
<ul> <li>Number of alarms for motion technology objects</li> </ul>	80
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	
Status/control variable	Yes
<ul><li>Variables</li></ul>	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
<ul> <li>Number of variables, max.</li> </ul>	
— of which status variables, max.	200; per job
<ul><li>of which control variables, max.</li></ul>	200; per job
Forcing	
Forcing, variables	Peripheral inputs/outputs
<ul> <li>Number of variables, max.</li> </ul>	200
Diagnostic buffer	
• present	Yes
<ul> <li>Number of entries, max.</li> </ul>	1 000
— of which powerfail-proof	500
Traces	
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	
Diagnostics indication LED	
• RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
STOP ACTIVE LED	Yes
<ul> <li>Connection display LINK TX/RX</li> </ul>	Yes

Motion Control  Ves; Note: The number of axes affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER  Number of available Motion Control resources for technology objects (except cam disks)  Required Motion Control resources  — per speed-controlled axis — per synchronous axis — per synchronous axis — per synchronous axis — per cam track — per probe  Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 4 ms (typical value)  PID_Compact PID_Compact PID_Compact PID_Compact PID_Compact PID_Compact PID_Step PID_Compact PID_Compact PID_Step PID_Compact PID_Step PID_Compact PID_Step PID_Controller with integrated optimization for valves Pes; PID controller with integrated optimization for temperature  Counting and measuring PID_Step PID_Compact PiD_Step PID_Compact PID_Step PID_Controller with integrated optimization for valves Pes; PID controller with integrated optimization for temperature  Counting and measuring Pid_speed counter  Ambient temperature during operation  Portical installation, min. Portical installation, min. Portical installation, min. Portical installation, max. Portical installation, min. Portical installation, max. Portical installation, min. Portical installation in min. Portical installation in min. Por	Supported technology objects	
Number of available Motion Control resources for technology objects (except cam disks)  Required Motion Control resources  — per speed-controlled axis  — per synchronous axis  — per synchronous axis  — per synchronous axis  — per output cam  — per cam track  — per probe  Positioning axis  — Number of positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at a motion control cycle of 8 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  PID_Compact  PID_Compact  PID_Step  PID_Temp  Counting and measuring  High-speed counter  Ambient conditions  Ambient temperature during operation  • horizontal installation, min.  • horizontal installation, max.  • vertical installation, max.  • v	Motion Control	Yes; Note: The number of axes affects the cycle time of the PLC
for technology objects (except cam disks)  Required Motion Control resources  — per speed-controlled axis  — per positioning axis  — per synchronous axis  — per output cam — per cuteral encoder — per output cam — per cam track — per positioning axes at motion control cycle of 4 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_Compact PID_Temp Yes; Universal PID controller with integrated optimization PID_Sistep PID_Temp Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Counting and measuring Pid_h-speed counter  Ambient temperature during operation  • horizontal installation, min. • horizontal installation, max.  • vertical installation, min. • vertical installation, max.  40 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off  Arbient temperature during storage/transportation  • rini. • vertical installation, max.  70 °C  Configuration  Programming  Programming language  — LAD — FBD — FB		program; selection guide via the TIA Selection Tool or SIZER
Required Motion Control resources  — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe  Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  PID_Compact PID_Compact PID_Sixep PID_Temp Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves PID_Sixep PID_Temp Yes; PID controller with integrated optimization for temperature Yes PID_Temp  Counting and measuring Pidis-speed counter Yes  Ambient temperature during operation  Norizontal installation, min. Norizontal installation, min. Norizontal installation, min. Norizontal installation, max. Norizontal installation, min. Norizontal installation,		800
- per speed-controlled axis		
— per positioning axis — per synchronous axis — per external encoder — per output cam — per cant track — per output cam — per cant track — per probe  • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller • PID_Compact • PID_Compact • PID_Tamp  Counting and measuring • PID_Temp  Counting and measuring • High-speed counter  Ambient conditions  Ambient temperature during operation • horizontal installation, min. • horizontal installation, min. • horizontal installation, min. • vertical installation, min. • vertical installation, max.  Ambient temperature during storage/transportation • rin. • vertical installation, max.  Ambient temperature during storage/transportation • min. • vertical installation, min. • vertical mistallation, min. •	<ul> <li>Required Motion Control resources</li> </ul>	
— per synchronous axis — per external encoder — per output cam — per cam track — per probe  • Postitioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  • PID_Compact • PID_Compact • PID_Step • PID_Temp  Counting and measuring • High-speed counter  Ambient conditions  Ambient temperature during operation • horizontal installation, min. • horizontal installation, min. • horizontal installation, min. • vertical installation, max. • vertical installation, max. • vertical installation, max.  Ambient temperature during storage/transportation • min. • vertical installation, max.  Ambient temperature during storage/transportation • min. • vertical mistallation, max.  Ambient temperature during storage/transportation • min. • vertical mistallation, max.  Yes  Configuration  Programming  Programming language  — LAD — FBD — STL  Yes	<ul><li>per speed-controlled axis</li></ul>	
— per external encoder — per output cam — per cam track — per probe 40  Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_Compact PID_Temp Yes; Universal PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Counting and measuring High-speed counter  Ambient conditions  Ambient temperature during operation Phorizontal installation, min. Phorizontal installation, min. Phorizontal installation, min. Porcitical installation, min. Porcitical installation, max.  Porcitical installat	— per positioning axis	80
- per output cam - per cam track - per probe - Positioning axis - Number of positioning axes at motion control cycle of 4 ms (typical value) - Number of positioning axes at motion control cycle of 8 ms (typical value) - Number of positioning axes at motion control cycle of 8 ms (typical value) - Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller - PID_Compact - PID_Compact - PID_Temp - Yes; PID controller with integrated optimization for valves - PID_Temp - Yes; PID controller with integrated optimization for temperature - PID_Temp - PiD-Temp - Yes; PID controller with integrated optimization for temperature - Yes - PID_Temp - Yes - PID_Temp - Yes - PID_Temp - Yes - PID_Temp - Yes	— per synchronous axis	160
— per cam track — per probe  • Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact • PID_Sompact • PID_Temp  Counting and measuring • High-speed counter  Ambient conditions  Ambient conditions  Ambient temperature during operation • horizontal installation, min. • horizontal installation, min. • vertical installation, max. • vertical inst	— per external encoder	80
- per probe Positioning axis - Number of positioning axes at motion control cycle of 4 ms (typical value) - Number of positioning axes at motion control cycle of 8 ms (typical value) - Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller PID_Compact PID_Compact PID_Temp Yes; Universal PID controller with integrated optimization of valves PID_Temp Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Counting and measuring High-speed counter  Ambient conditions  Ambient temperature during operation horizontal installation, min. horizontal installation, max.  O °C C, the display is switched off vertical installation, max.	— per output cam	20
Positioning axis  - Number of positioning axes at motion control cycle of 4 ms (typical value)  - Number of positioning axes at motion control cycle of 8 ms (typical value)  - Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact  • PID_Compact  • PID_Temp  Yes; Universal PID controller with integrated optimization for valves  • PID_Temp  Counting and measuring  • High-speed counter  Ambient conditions  Ambient temperature during operation  • horizontal installation, min.  • horizontal installation, min.  • horizontal installation, min.  • vertical installation, min.  • vertical installation, max.  Ambient temperature during storage/transportation  • win.  • vertical installation, max.  Ambient temperature during storage/transportation  • min.  • max.  70 °C  Configuration  Programming  Programming language  - LAD - FBD - STL  - STL  Yes	— per cam track	160
- Number of positioning axes at motion control cycle of 4 ms (typical value) - Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  • PID_Compact • PID_SStep • PID_Temp  Counting and measuring • High-speed counter  Ambient temperature during operation • horizontal installation, min. • horizontal installation, min. • vertical installation, min. • vertical installation, max. • vertical installation, max.  • vertical installation	— per probe	40
control cycle of 4 ms (typical value)  Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact  PID_Step  PID_Temp  Counting and measuring  High-speed counter  Phorizontal installation, min.  Profrain installation, min.  vertical installation, min.  vertical installation, max.  Pertical installation, max.  Configuration  Programming  Pr	Positioning axis	
- Number of positioning axes at motion control cycle of 8 ms (typical value)  Controller  PID_Compact PID_Sistep PID-Temp Yes; PID controller with integrated optimization for valves PID-Temp Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Counting and measuring High-speed counter  Ambient conditions  Ambient temperature during operation  No "C Horizontal installation, min. No "C Ho	<ul> <li>Number of positioning axes at motion</li> </ul>	5
control cycle of 8 ms (typical value)  Controller  PID_Compact PID_Dempact PID_Dempact PID_Temp PID_Temp PID_Temp PID_Temp Pigh-speed counter  Ambient temperature during operation Portical installation, min. Programming Programming Programming Programming language  LAD PFBD PSTL  Yes  Yes  Yes  Yes  Yes  Yes  Yes  Ye	control cycle of 4 ms (typical value)	
Controller  PID_Compact PID_Step PID_Temp Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Counting and measuring High-speed counter Yes  Ambient conditions  Ambient temperature during operation  horizontal installation, min. horizontal installation, max.  60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off  vertical installation, max.  40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off  Ambient temperature during storage/transportation  min. min. min.  40 °C  70 °C  Configuration  Programming  Programming language  LAD FBD PSTL Yes	• • • •	10
PID_Compact PID_3Step PID_Temp Yes; PID controller with integrated optimization for valves PID_Temp Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for valves Yes; PID controller with integrated optimization for temperature  Counting and measuring High-speed counter  Ambient conditions  Ambient temperature during operation  No "C Horizontal installation, min. Horizontal installation, max.  O "C C, the display: 50 "C, at an operating temperature of typically 50 "C, the display is switched off  Vertical installation, max.  Vertical installation, max.  Vertical installation, max.  O "C To bisplay: 40 "C, at an operating temperature of typically 40 "C, the display is switched off  Ambient temperature during storage/transportation  min.  min.  max.  70 "C  Configuration  Programming  Programming  Programming language  LAD FBD FBD Yes STL Yes		
PID_3Step PID-Temp PID-Temp Pigh-speed counter  Ambient conditions Ambient temperature during operation  horizontal installation, min. horizontal installation, min.  vertical installation, max.  vertical installation installation, max.  vertical installation, max.  vertical installation, max.  vertical installation, max.  vertical installation installation, max.  vertical installation installation installation, max.  vertical installation install	Controller	
PID-Temp  Yes; PID controller with integrated optimization for temperature  Counting and measuring  High-speed counter  Yes  Ambient conditions  Ambient temperature during operation  horizontal installation, min.  horizontal installation, max.  60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off  vertical installation, min.  vertical installation, max.  40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off  Ambient temperature during storage/transportation  min.  min.  40 °C  70 °C  Configuration  Programming  Programming  Programming language  — LAD — FBD — STL  Yes  Yes	<ul><li>PID_Compact</li></ul>	Yes; Universal PID controller with integrated optimization
Counting and measuring  • High-speed counter  Ambient conditions  Ambient temperature during operation  • horizontal installation, min. • horizontal installation, max. • oo °C, Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off • vertical installation, min. • vertical installation, max. • vertical installation, max.  • vertical installation, max.  • vertical installation, max.  • vertical installation, max.  • o°C, Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off  Ambient temperature during storage/transportation  • min. • 40 °C  • max.  • o°C  Configuration  Programming  Programming  Programming language  — LAD — FBD — STL  Yes	• PID_3Step	Yes; PID controller with integrated optimization for valves
High-speed counter  Ambient conditions  Ambient temperature during operation      horizontal installation, min.     horizontal installation, max.     horizontal installation, max.     horizontal installation, min.     vertical installation, min.     vertical installation, max.     horizontal installation, min.     vertical installation, max.     vertical installation, min.     vertical installation of conclusion of conc	PID-Temp	Yes; PID controller with integrated optimization for temperature
Ambient conditions  Ambient temperature during operation  • horizontal installation, min. • horizontal installation, max.  • horizontal installation, max.  • vertical installation, min. • vertical installation, max.  • vertical installation, min.  • vertical installation installation, min.  • vertical installation installa	Counting and measuring	
Ambient temperature during operation  • horizontal installation, min. • horizontal installation, max.  • horizontal installation, max.  • horizontal installation, max.  • oo °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off  • vertical installation, min.  • vertical installation, max.  • vertical installation, max.  • vertical installation, max.  • oo °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off  Ambient temperature during storage/transportation  • min.  • min.  • 40 °C  To °C  Configuration  Programming  Programming language  — LAD  — FBD  — STL  Yes  Yes	High-speed counter	Yes
<ul> <li>horizontal installation, min.</li> <li>horizontal installation, max.</li> <li>60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off</li> <li>vertical installation, min.</li> <li>vertical installation, max.</li> <li>40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off</li> <li>Ambient temperature during storage/transportation</li> <li>min.</li> <li>-40 °C</li> <li>max.</li> <li>70 °C</li> <li>Configuration</li> <li>Programming</li> <li>Programming language</li> <li>— LAD</li> <li>— FBD</li> <li>— FBD</li> <li>— STL</li> <li>Yes</li> <li>Yes</li> <li>Yes</li> </ul>	Ambient conditions	
<ul> <li>horizontal installation, max.</li> <li>60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off</li> <li>vertical installation, min.</li> <li>0 °C</li> <li>vertical installation, max.</li> <li>40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off</li> <li>Ambient temperature during storage/transportation</li> <li>min.</li> <li>-40 °C</li> <li>max.</li> <li>70 °C</li> <li>Configuration</li> <li>Programming</li> <li>Programming language</li> <li>LAD</li> <li>FBD</li> <li>Yes</li> <li>STL</li> <li>Yes</li> <li>Yes</li> </ul>	Ambient temperature during operation	
<ul> <li>°C, the display is switched off</li> <li>0 °C</li> <li>vertical installation, min.</li> <li>40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off</li> <li>Ambient temperature during storage/transportation</li> <li>min.</li> <li>-40 °C</li> <li>max.</li> <li>70 °C</li> </ul> Configuration Programming Programming language <ul> <li>LAD</li> <li>FBD</li> <li>FBD</li> <li>Yes</li> <li>Yes</li> <li>Yes</li> <li>Yes</li> </ul> Yes <ul> <li>Yes</li> <li>Yes</li> </ul> Yes <ul> <li>Yes</li> <li>Yes</li> </ul> Yes <ul> <li>Yes</li> <li>Yes</li> </ul> Yes <ul> <li>Yes</li> <li>Yes</li> </ul> Yes <ul> <li>Yes</li> </ul> Yes <ul> <li>Yes</li> <li>Yes</li> </ul> Yes <	horizontal installation, min.	0 °C
<ul> <li>vertical installation, max.</li> <li>40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off</li> <li>Ambient temperature during storage/transportation</li> <li>min.</li> <li>-40 °C</li> <li>max.</li> <li>70 °C</li> <li>Configuration</li> <li>Programming</li> <li>Programming language</li> <li>LAD</li> <li>FBD</li> <li>Yes</li> <li>STL</li> <li>Yes</li> <li>Yes</li> <li>Yes</li> </ul>	• horizontal installation, max.	
°C, the display is switched off  Ambient temperature during storage/transportation  • min.  • max.  70 °C  Configuration  Programming  Programming language  — LAD — FBD — FBD — STL  Yes  Yes	• vertical installation, min.	0 °C
	• vertical installation, max.	
<ul> <li>● max.</li> <li>To °C</li> <li>Configuration</li> <li>Programming</li> <li>Programming language</li> <li>— LAD</li> <li>— FBD</li> <li>— STL</li> <li>Yes</li> <li>Yes</li> <li>Yes</li> </ul>	Ambient temperature during storage/transportation	
Configuration  Programming  Programming language  — LAD Yes  — FBD Yes  — STL Yes	• min.	-40 °C
Programming  Programming language  — LAD Yes  — FBD Yes  — STL Yes	• max.	70 °C
Programming language  — LAD Yes  — FBD Yes  — STL Yes	Configuration	
— LAD       Yes         — FBD       Yes         — STL       Yes	Programming	
<ul><li>FBD</li><li>STL</li><li>Yes</li><li>Yes</li></ul>	Programming language	
— STL Yes	— LAD	Yes
	— FBD	Yes
— SCL Yes	— STL	Yes
	— SCL	Yes

— GRAPH	Yes
Know-how protection	
User program protection/password protection	Yes
Copy protection	Yes
<ul> <li>Block protection</li> </ul>	Yes
Access protection	
Password for display	Yes
<ul> <li>Protection level: Write protection</li> </ul>	Yes
<ul> <li>Protection level: Read/write protection</li> </ul>	Yes
<ul> <li>Protection level: Complete protection</li> </ul>	Yes
Cycle time monitoring	
• lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	35 mm
Height	147 mm
Depth	129 mm
Weights	
Weight, approx.	405 g