

GENERAL FEATURES

- Pulse input for all the most commonly-used sensors: mechanical contact, reed, non with 2 and 4 wires, pnp with 3 wires and 24V DC power supply, Namur, photoelectric, variable reluctance, 24V and TTL pulses
- Maximum frequency from 1 mHz to 9.99 KHz, selectable fullscale from 10 mHz to 9.99 KHz:
- Full-scale can be easily set using rotating switches;
 Selection of the output mode (0/4.20 mA, 0/1..5V, 0/2..10V) using dip-switches;
- · Possibility to set the number of pulses for the calculation of the pulse average;
- Indication of power supply presence and out-of-scale errors provided on front panel;
- 3-point insulation: 1500V AC

TECHNICAL SPECIFICATIONS

Power supply:	1940 Vdc, 1928 Vac 5060 Hz, max 2,5 W	
Input:	Pulses: mechanical contact, reed , npn with 2 and 3 wires , pnp with 3 wires and 24V DC power supply, Namur, photoelectric, "HALL" sensor, and variable reluctance. Maximum frequency 9.99 KHz	
Output:	Active current 020 mA / 420 mA, max. load resistance: 600 ohm Voltage 05 V / 010 V / 15 V / 210 V , min. load resistance: 2500 ohm Error : < 0.3% of F.S.	
Work conditions:	Temperature: 0 - 50°C , Min. humidity: 30% , Max. humidity: 90% at 40°C (non condensing)	
Standards: C LISTED JLUT	The instrument conforms to the following standards: EN60081-2 (electromagnetic amission, industrial environments) EN60082-2 (electromagnetic immunity, industrial environments) EN61010-1 (safety) Notes: - Use with copper conductor. - Use in Pollution Degree 2 Environment. - Power Supply must be Class 2. - When supplied by an isolated Limited Voltage/Limited Current power supply a lase rated max 2.5A shall be installed in the field.	
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INSTALLATION RULES

The Z111 modules have been designed for mounting on DIN 46277 guides in vertical position

For long-lasting and optimum working life, the module(s) must be ensured adequate ventilation. Make sure to position the cable raceways and any other objects in such way as to avoid clogging the ventilation slots.

Also avoid positioning the modules above equipment that generates heat. For this reason, we recommend performing installation in the lower part of the panel.

TAXING WORK CONDITIONS:

- The following are considered taxing work conditions:
- elevated power supply voltage (> 30V DC / > 26 V AC)
- · providing power supply to sensor input. use of the active current output.

When paired modules are installed, they may require separation by at least 5 mm in the following cases:

- · With panel temperatures of more than 45°C in concomitance with at least one of the taxing work conditions above.
- With panel temperatures of more than 35°C in concomitance with at least two of the taxing work conditions above.

ELECTRICAL CONNECTIONS

We recommend using shielded cables for the connection of the signals; the shield must be connected to a designated ground connection for the instrumentation. We also discourage passing the wires near the power supply cables for inverters, motors, or induction ovens etc.

POWER SUPPLY

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jumpers must be selected.

set for standard inputs.

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- The power supply voltage must be between 19 and 40 V DC **2** <u>19 ÷ 28 V</u>~ (polarity not important), 19 and 28 V AC; also see the section ____ 19 ÷ 40 V= entitled "INSTALLATION RULES".
 - The upper limits must never be exceeded at the risk of creating serious damage to the module. The power supply source must be protected against all risk of module malfunction

by the use of an well sized fuse



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NOTE : In order to permit the use of the variable reluctance type input, the internal

removed by pulling it slightly outward. The instrument is supplied with internal iumpers

Before setting the internal jumpers, the container's lateral closing panel must be

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This operation is only performed when the "variable reluctance" input is used For the hysteresis calibration, after first correctly setting the internal jumpers and the fullscale frequency, a tester must be connected to the device's output (it makes no difference whether the voltage or current output is used) and an input signal must be provided; then using a screwdriver, rotate the hysteresis trimmer completely counter-clockwise (the tester should indicate 0) and then the trimmer must be slowly rotated clockwise until the tester provides a stable input reading. At this point, rotate the trimmer clockwise by around 5% in order to have a sufficient calibration safety margin NOTE : remember that the minimum signal amplitude is 100 mV.

RETRANSMITTED OUTPUT



SW6 - FILTER Whenever the input frequency is unstable, a filter can be set to stabilise the output signal. In order to set this filter, position Filter OFF SW6 dip-switch no. 1 in the ON position (by shifting it Filter ON upwards)

N.B.: The dip-switches must be set after first disconnecting power supply from the module in order to avoid damaging the module

RESPONSE TIME

RANGE	RESPONSE TIME	Led error after	
x 0,0001	25 sec	1000 sec	
x 0,001	2,5 sec	100 sec	
x 0,01	0,25 sec	10 sec	
x 0,1	0,25 sec	10 sec	
x 1	0,25 sec	10 sec	
x 10	0,25 sec	10 sec	

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INPUT FREQUENCY SETTING

The input signal full-scale frequency can be easily set.

The three rotating selectors permit the setting of a value which when multiplied by the multiplication factor will provide the input signal full-scale frequency.

- Example 1: if the input frequency full-scale value = 563 Hz, the hundredths (100's) selector must be set to 5, the tenths (10's) selector must be set to 6, and the units (1's) selector must be set to 3. The multiplier must be set to x 1 (563 x 1 = 563 Hz).
- Example 2: if the input frequency full-scale value = 7850 Hz, the hundredths (100's) selector must be set to 7, the tenths (10's) selector must be set to 8, and the units (1's) selector must be set to 5. The multiplier must be set to x 10 (7850 x 10 = 7850 Hz).
- NOTE 1: The hundredths selector (100's) cannot be set to 0; the minimum full-scale value must therefore be 0,01 Hz.
- NOTE 2 : The "Error" led blink if the input frequency is less lower than the values indicated in the table or more than selected fullscale

Multiplier setting Frequency setting selectors



disconnecting module power supply in order to avoid damaging the module.

PULSE AVERAGE SETTING

Whenever the input signals present cyclically unstable frequency, a number of pulses on which the frequency measurement will be calculated can be set

Example : the input signal is provided by a proximity sensor that indicates the passage of a number of bolts mounted on a wheel; if these bolts are not positioned at equal distances, an unstable sensor output frequency value will occur and this will create an unstable module Z11 output current and/or voltage value

By setting the number of bolts applied to the wheel, such as 10, for example, as the "pulse average", the device will count 10 pulses and then divide the time that elapses between the first and the last pulse by 10. This operation will permit an extremely stable module output signal to be obtained.

ilter can be set is filter, position hifting it rst tule in order to	SW7 - PULSE AVERAGE	NOTE : if pulse average required, leave all the S switches OFF (shifted (NOTE: Dip-switch sett performed after first d power supply in order the module. NOTE: The minimum normally 0.001Hz. Whe set over 6, the minimum 6000. Ex: pulse average = 8, f.min = 8/6000 = 0.0013	e calculation is not W7 selector dip- down). ing must be isconnecting module to avoid damaging easured frequency is n the pulse average is n frequency will be n / i3Hz.
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OUTPUT SELECTION

SW1 - OUTPUT MODE	CM/4 white dis assistance assertion 4 and 0 according		
020mA/05V/010V	setting the setting of the output with or without		
420mA/15V/210V	zero elevation respectively. SW2 unit dip-switches permit the selection of		
SW2 - OUTPUT VOLTAGE	the output voltage.		
0/15V	NOTE: Dip-switch setting must be		
0/210V	performed after first disconnecting module		
	the module.		





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SW1 JP5-JP6 SW2

>100mV



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